

# Intra-Vehicle Wireless Communications: Challenges and Potential Solution

**Xiao-Hong Peng**

Faculty of Computing, Engineering and the Built Environment

Birmingham City University, UK.

[xiahong.peng@bcu.ac.uk](mailto:xiahong.peng@bcu.ac.uk)



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2020

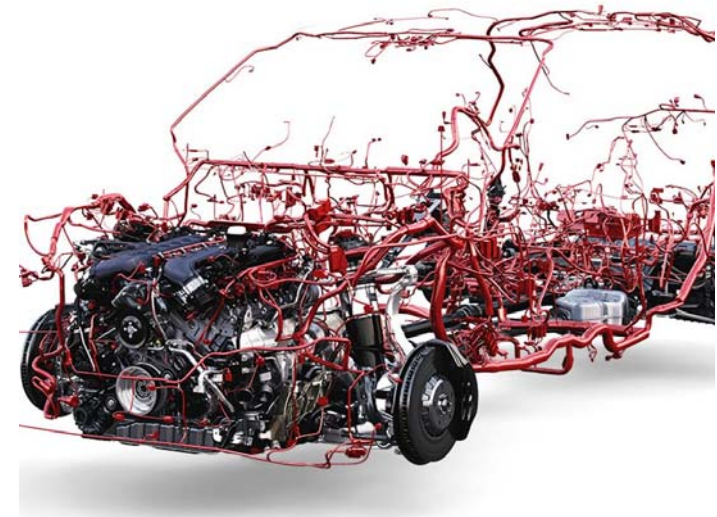
# OUTLINE

- ❖ Introduction
  - Why wireless communications in a vehicle
  - Challenges
  - Our research
- ❖ Intra-vehicle wireless channels
  - Multipath
  - Interference
  - Testbed
- ❖ Fading characteristics and loss performance
  - Power delay, RMS delay, coherence bandwidth
  - Rician k-factor
- ❖ Impacts of channel loss and electromagnetic interference on intra-vehicle wireless communications
  - EMI burst length
  - EMI gap
- ❖ Potential solution & Conclusion

# INTRODUCTION

## Why do we need wireless communications in vehicles?

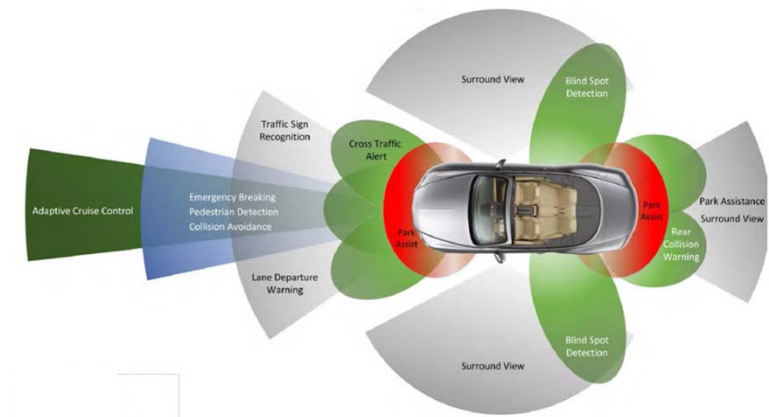
- ❖ The numbers of electronic devices and sensors used in vehicles have been increased significantly over the years.
  - The number of electric control units (ECU) in a car is increased from 75 (2010) to 150 (2019).
  - Today, electronic devices are responsible for 40% of the cost of a vehicle, as compared to 18% in 2000.
- ❖ The wire connections to those devices have caused serious wire harness problems.
  - It is the third most heaviest component after the chassis and engine.
  - Can weight as much as 60 kg per car.



# INTRODUCTION (CONT.)

## What is the development trend of new-generation vehicles?

- ❖ New features and functionality
  - Increased number of sensors for safety
  - Autonomous driving
  - Greener
- ❖ The benefits offered by wireless solutions:
  - Save physical space
  - Reduce weight
  - Increased fuel efficiency



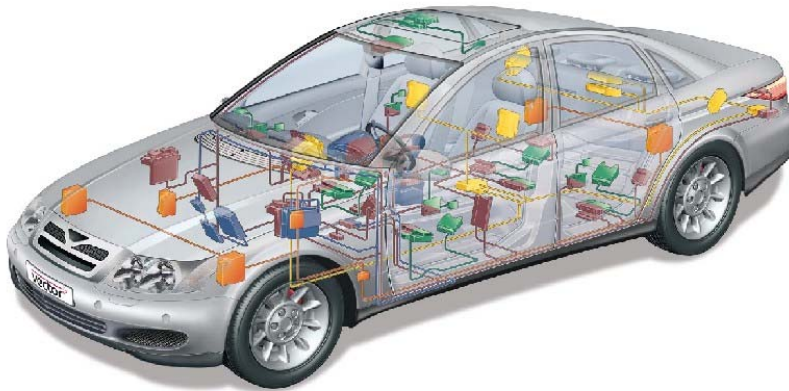
# INTRODUCTION (CONT.)

## What we face and should do?

- ❖ Wireless communications currently adopted inside vehicles:
  - Bluetooth and WiFi for the infotainment system
  - GNSS for navigation
  - Tire pressure monitoring system (TPMS)
- ❖ Challenges:
  - Inherent vulnerability of wireless transmission.
  - Complex wireless channel conditions within a small enclosure.
  - Co-existence of multiple wireless signals with varied protocols.
- ❖ Our research:
  - Investigation of intra-vehicle wireless channel properties
  - Unveil data transmission performance in such a environment
  - Design of intra-vehicle wireless communications and networking protocols



# INTRODUCTION - INTRA-VEHICLE NETWORK ARCHITECTURE



Wireless option: to reducing cabling and improve fuel efficiency



## Concerns:

- Reliability
- Safety
- Scalability

## Applications of Intra-Vehicle Network:

- Control of steering wheel, windows, seat positions, lighting
- Detecting road events
- Traffic monitoring
- Fuel economy and emission monitoring and control
- Driver behaviour detection
- Entertainment



# INTRA-VEHICLE WIRELESS CHANNELS

# CHANNEL CHARACTERISTICS

## ❖ Environmental conditions:

- Electronic systems inside vehicles are much more complex than decades ago  
→ more radiated emissions and noise sources.
- Multipath – multiple copies of the same signal are generated in a small enclosure with various types of obstacles.
- None-line-of-sight – transmission links between transmitters and receivers are likely to be blocked by seats, devices and passengers.

## ❖ Performance measurements:

- Channel loss (Path loss)
- Power profile
- Delay profile



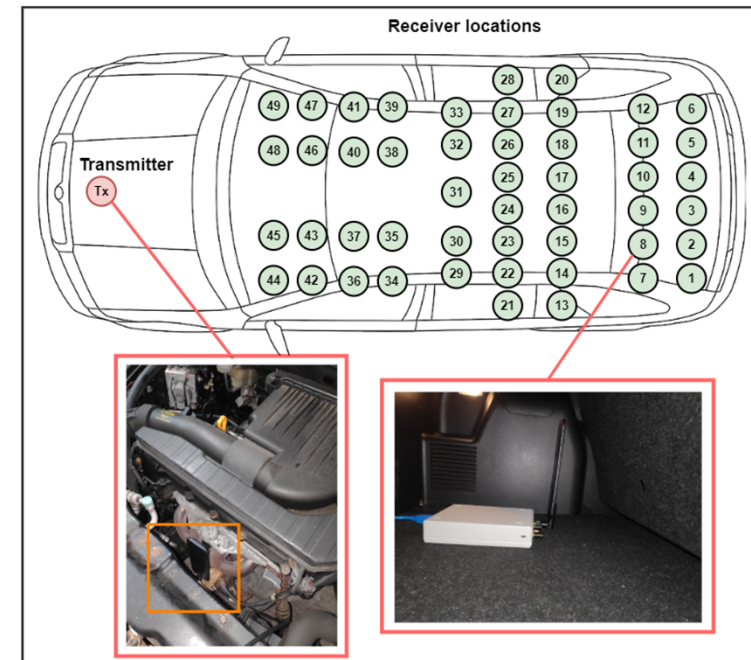
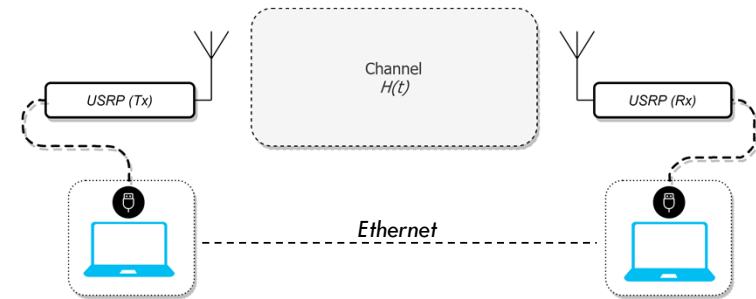
# TESTBED SETUP

## ❖ Equipment and settings

- 2x Ettus USRP B210 (Software Defined Radio)
- 2x Laptop
- Omnidirectional antenna
- 2 GHz – 3 GHz
- Transmitter (Tx) power : 0 dBm

## ❖ Testing locations

- Engine compartment
- Passenger compartment: 49 locations

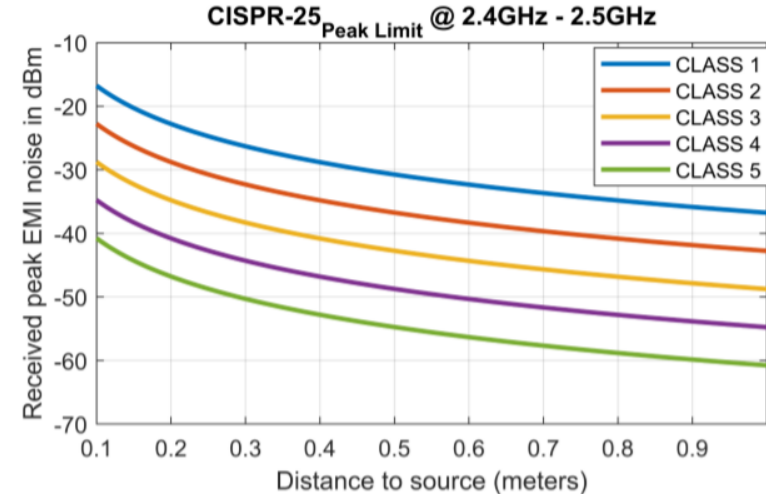
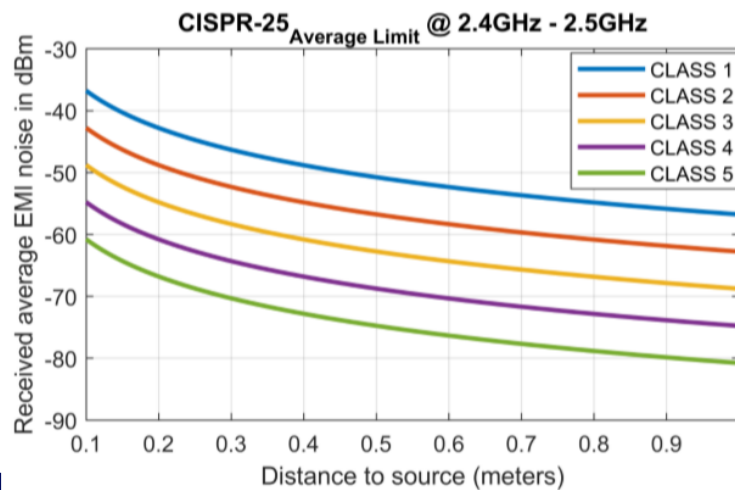


# ELECTROMAGNETIC INTERFERENCE (EMI)

- ❖ Two primary CISPR standards commonly applied:
  - CISPR-25 (as a reference for our research)
  - CISPR-12
- ❖ CISPR-25
  - Guidelines for assessing electrical devices in a vehicle.
  - The standards specifying the peak, average and quasi-peak limits for different frequency bands.
- ❖ Estimation of the detailed feature of EMI within a close proximity to EMI sources.
  - Convert the peak and average limits of the electric field strength in dBuV/m into a power level in dBm.

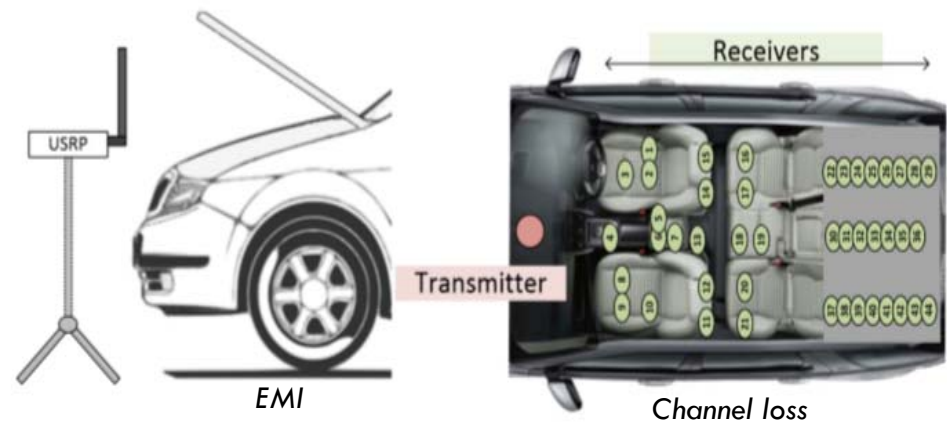
# AVERAGE AND PEAK LIMITS

- ❖ A receiver will experience higher interference when being placed near to an EMI source.
- ❖ UWB (Ultra-Wideband) based solutions experience significant interference from EMI, compared to the narrowband-based or broadband-based solutions.



# EXPERIMENTS

- ❖ A purpose-built testbed.
  - Channel loss
  - EMI
- ❖ Channel Loss
  - Two USRP B210
  - Omnidirectional antenna
  - Frequency: 2.4 GHz
- ❖ EMI
  - One USRP B210
  - Frequency: 2.4 GHz
  - 1 meter away from the engine compartment

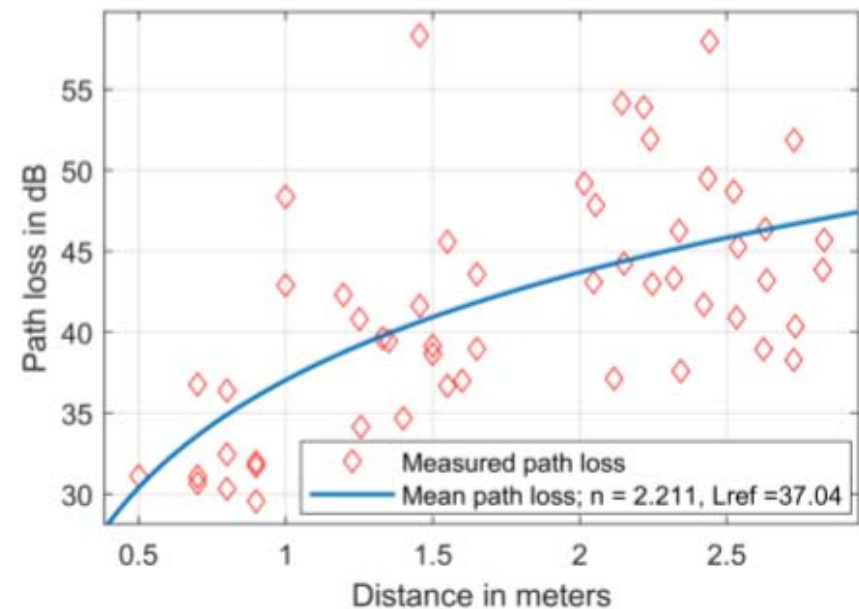




# FADING CHARACTERISTICS AND LOSS PERFORMANCE

# PATH LOSS

- ❖ Calculated from the measured received power.
  - Mean path loss is estimated using the Linear Regression method.
  - The loss exponent ( $\alpha$ ) extracted is close to the free space path loss. ( $\alpha = 2$ )
- ❖ Multipath fading is the main contributor to the overall path loss.
  - The maximum fade depth or variation is measured as 18.5 dB.
  - The difference between the measured value and its local mean loss reflects fading properties.

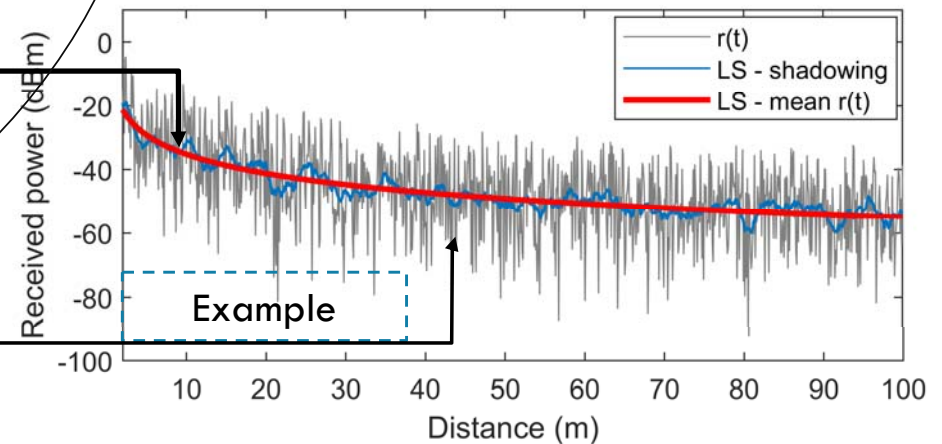


# EXTRACTING THE LARGE-SCALE AND SMALL-SCALE FADING COMPONENTS

$$L_p = L_m + \Psi_\alpha + \beta_s$$

The power measured at different locations is further processed to extract:

- ❖ Large-scale fading (LS)
  - Slow-varying signal envelope
  - Shadowing + mean  $r(t)$
- ❖ Small-scale fading
  - Fast changing received signal envelope



# LEE ANALYTICAL METHOD

$$r(x) = \underbrace{\Psi_{\alpha}(x)}_{\text{Large-scale fading}} \underbrace{\beta_s(x)}_{\text{Small-scale fading}}$$

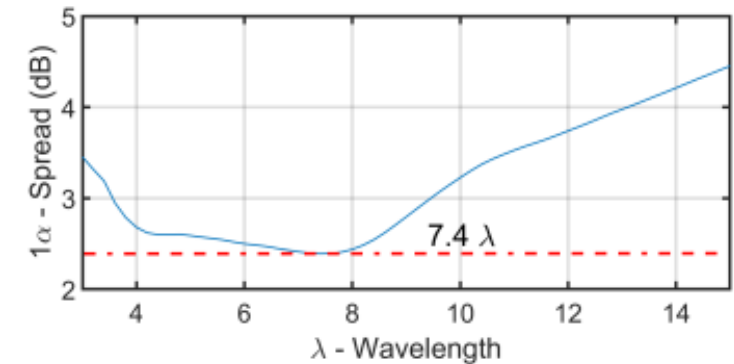
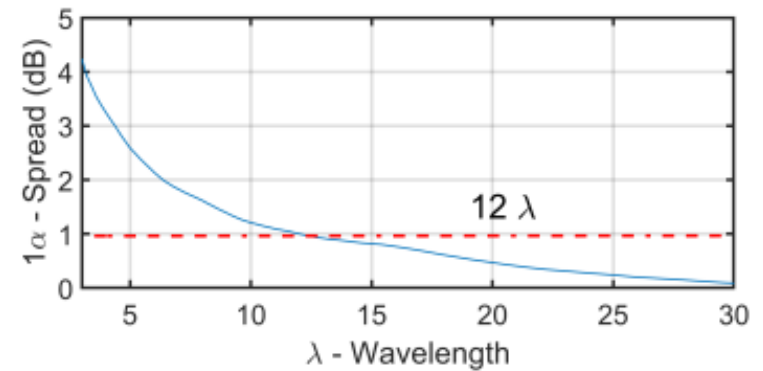
The large-scale fading is extracted by averaging the samples using an appropriately chosen averaging length ( $2L$ )

$$\hat{r}(x) = \frac{1}{2L} \int_{x-L}^{x+L} \Psi_{\alpha}(y) \beta_s(y) dy$$

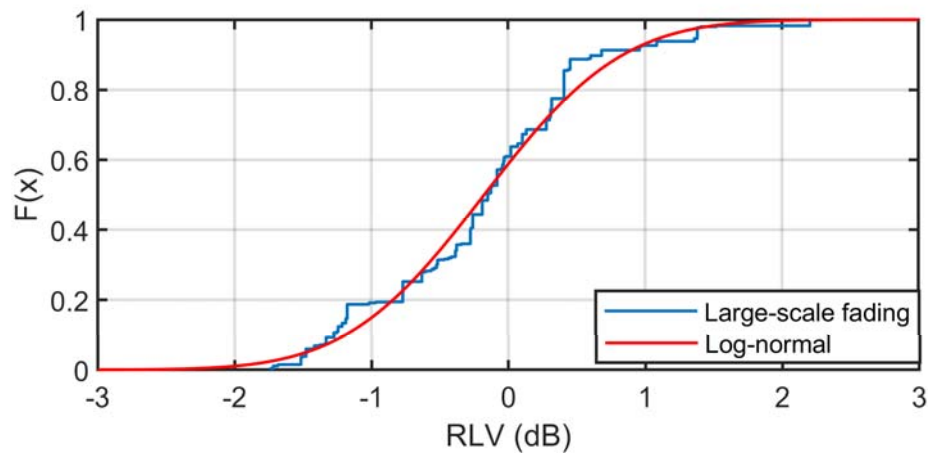


# METHODS OF EXTRACTING FADING COMPONENTS

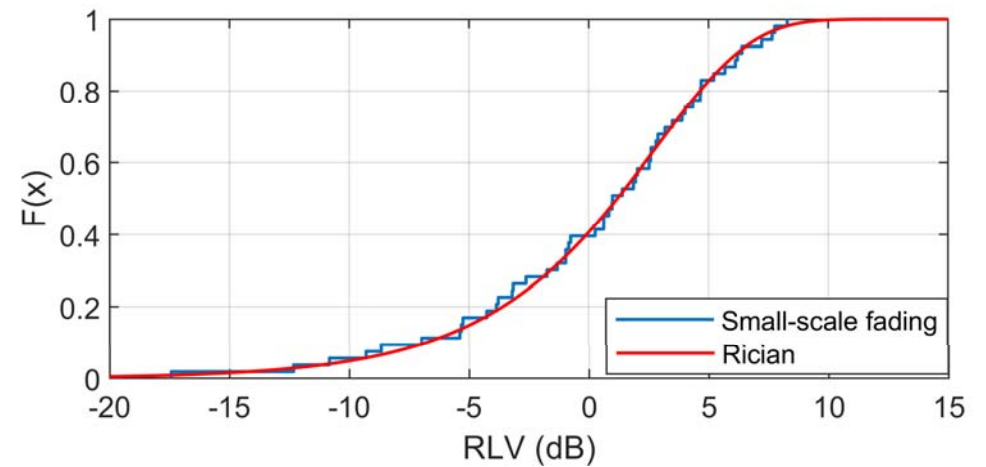
1. Lee analytical method
  - Upper bound of averaging length ( $2L$ )
2. Generalized Lee method
  - Optimum averaging length ( $2L$ )



# DISTRIBUTION OF LARGE-SCALE AND SMALL-SCALE FADING



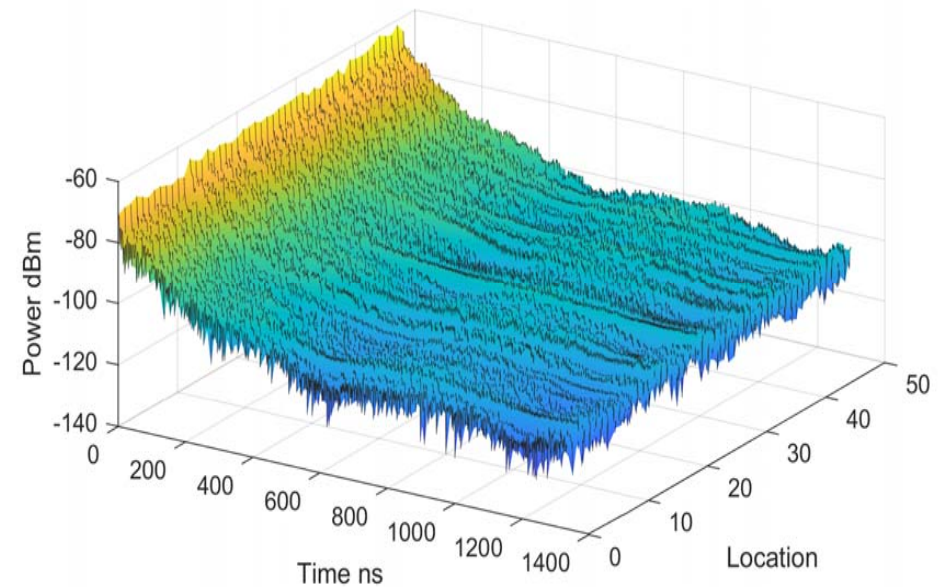
- Large-scale fading statistics.



- Small-scale fading statistics - much more dominant than large-scale fading.

# POWER DELAY PROFILE

- ❖ The power delay profile is estimated using the inverse discrete Fourier transform (IDFT) with a Hanning window ( $W(f)$ ).
- ❖ Demonstrate consistent trend across all 49 locations.
- ❖ Exponential decay with time ( $t$ ).



# ROOT MEAN SQUARE (RMS) DELAY SPREAD

## ❖ RMS delay spread

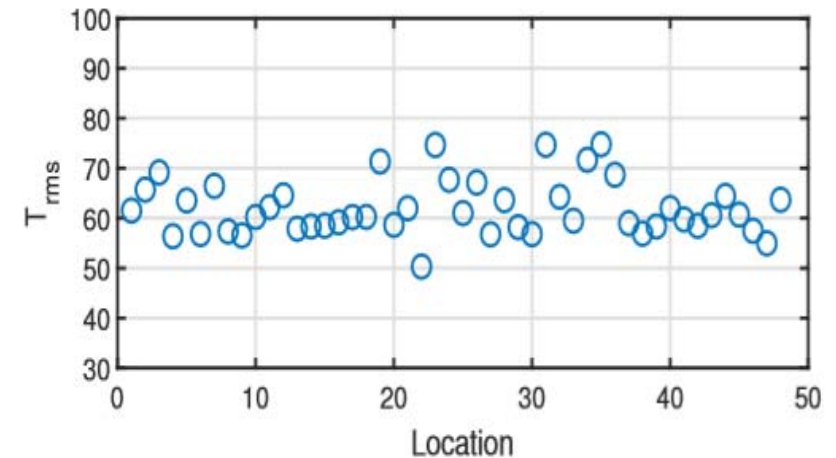
- The square root of the second central moment of the power delay profile

$$\sigma_{\tau} = \sqrt{\overline{\tau^2} - \bar{\tau}^2}$$

- The delay spread ( $T_{rms}$ ) varies between 50 –Low c 75 ns  
Average = 60.72 ns
- Higher than the values measured in other environments (indoor, industrial, underground tunnel etc.)

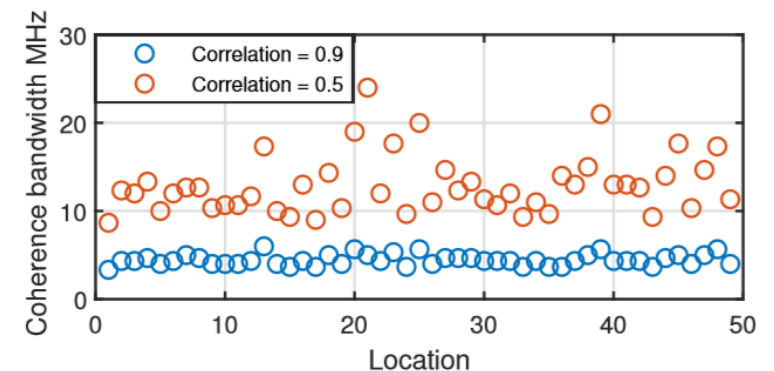
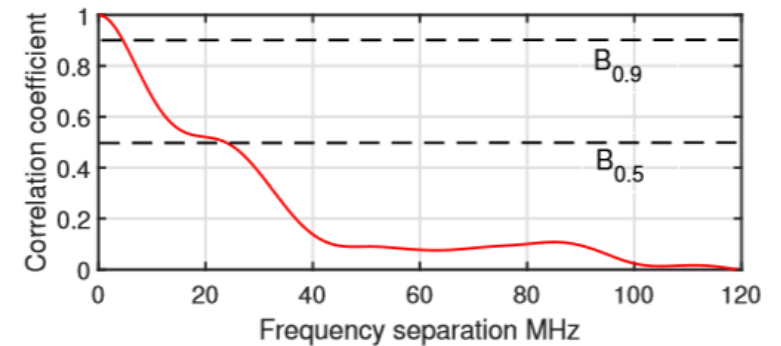
## ❖ Pearson correlation test

- Low correlation with distance ( $\rho = -0.02$ )



# COHERENCE BANDWIDTH

- ❖ The coherence bandwidth was evaluated from the frequency correlation function (autocorrelation) of the frequency response of the channel.
  - Evaluated for correlation levels of 0.5 and 0.9.
  - Coherence bandwidth range:  $B_{0.5} = 8.4 \text{ MHz} - 24 \text{ MHz}$
  - Average = 12.95 MHz
- ❖ Pearson correlation test
  - Low correlated with distance
  - $B_{0.9}$  ( $\rho = -0.103$ ) and  $B_{0.5}$  ( $\rho = -0.194$ )



# RICIAN K-FACTOR ANALYSIS

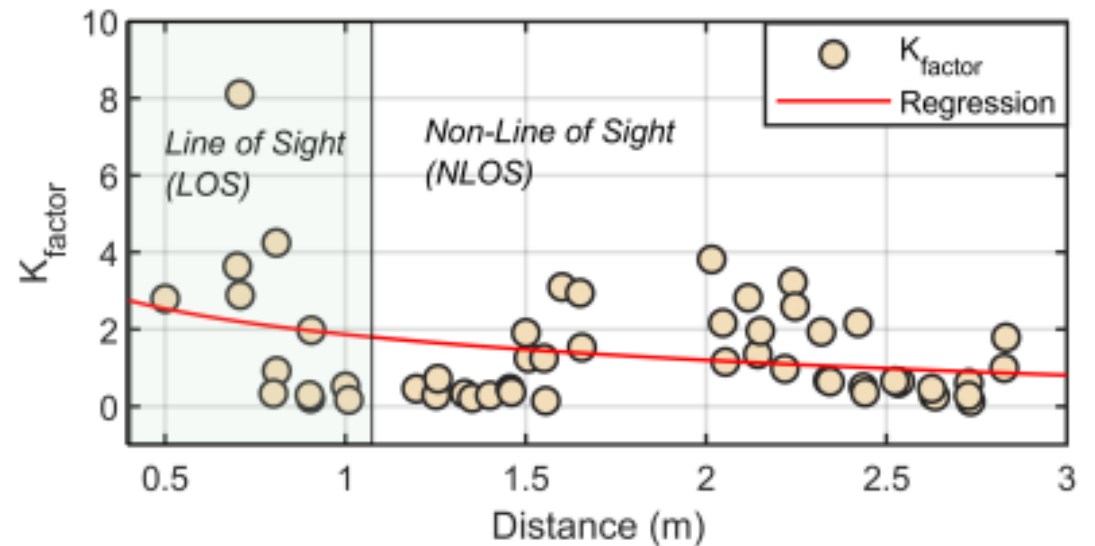
- ❖ The k-factor helps to decide the type of channels: Rayleigh or Rician?
  - Rician K-factor is the ratio of the dominant path to the diffuse component (multipath).

$$K = \frac{|A|^2}{\sigma^2}$$

- ❖ There are various methods that exist in defining or estimating Specular and Diffuse components.
  - Method of moment – does not require phase information.

# K-FACTOR AGAINST DISTANCE

- The K-factor vary with distance with the average K-factor  $\approx 0.5$  (-13 dB)
- The intra-vehicle channel can be treated as a near-Rayleigh channel.



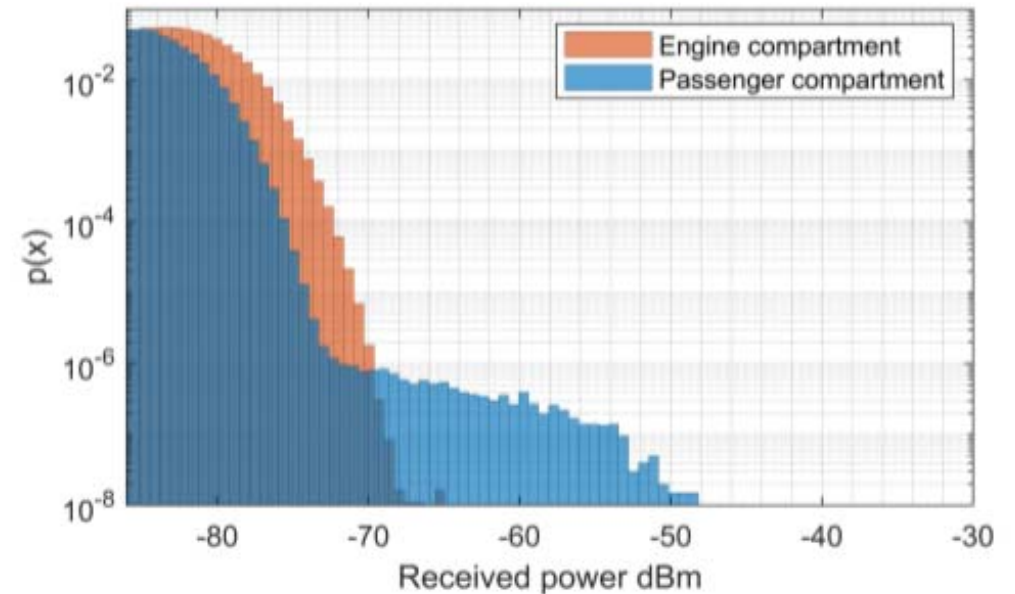


# IMPACTS OF CHANNEL LOSS AND ELECTROMAGNETIC INTERFERENCE ON INTRA- VEHICLE WIRELESS COMMUNICATIONS



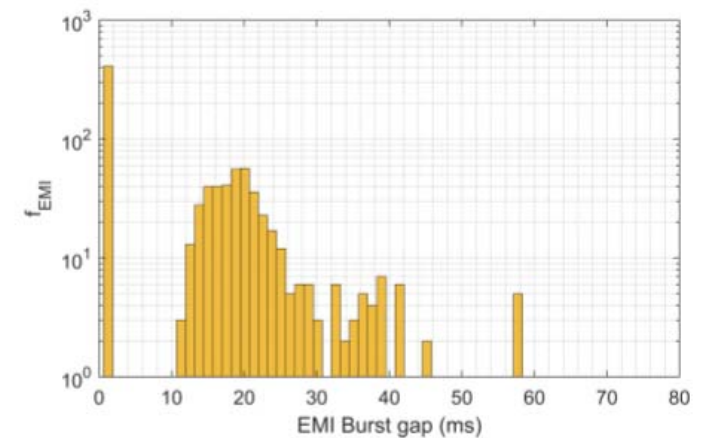
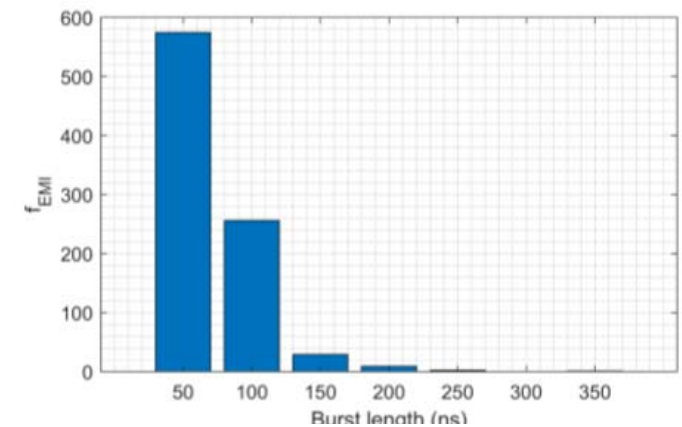
# EMI PROPERTY

- ❖ Measured as the probability density against the time-series received power.
  - In both engine and passenger compartments
- ❖ Engine compartment
  - Peak EMI: -48.53 dBm
  - Average EMI: -62.01 dBm
- ❖ Passenger compartment
  - Peak EMI: -62.6 dBm
  - Average EMI: -88.47 dBm



# EMI BURST LENGTH AND GAP

- ❖ EMI burst length - the time period of the interfering signal.
- ❖ EMI burst gap - the length(gap) between two interfering signals.
- ❖ Short EMI burst (50 ns) is more likely to occur than longer burst.
- ❖ A high number of EMI bursts within a short amount of time (200 ns).



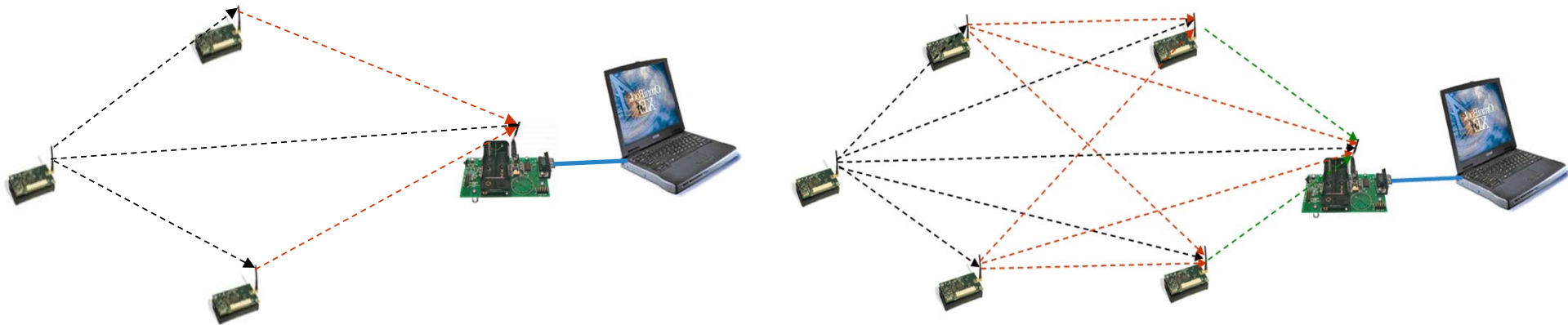


# POTENTIAL SOLUTION

# CROSS-LAYER APPROACH

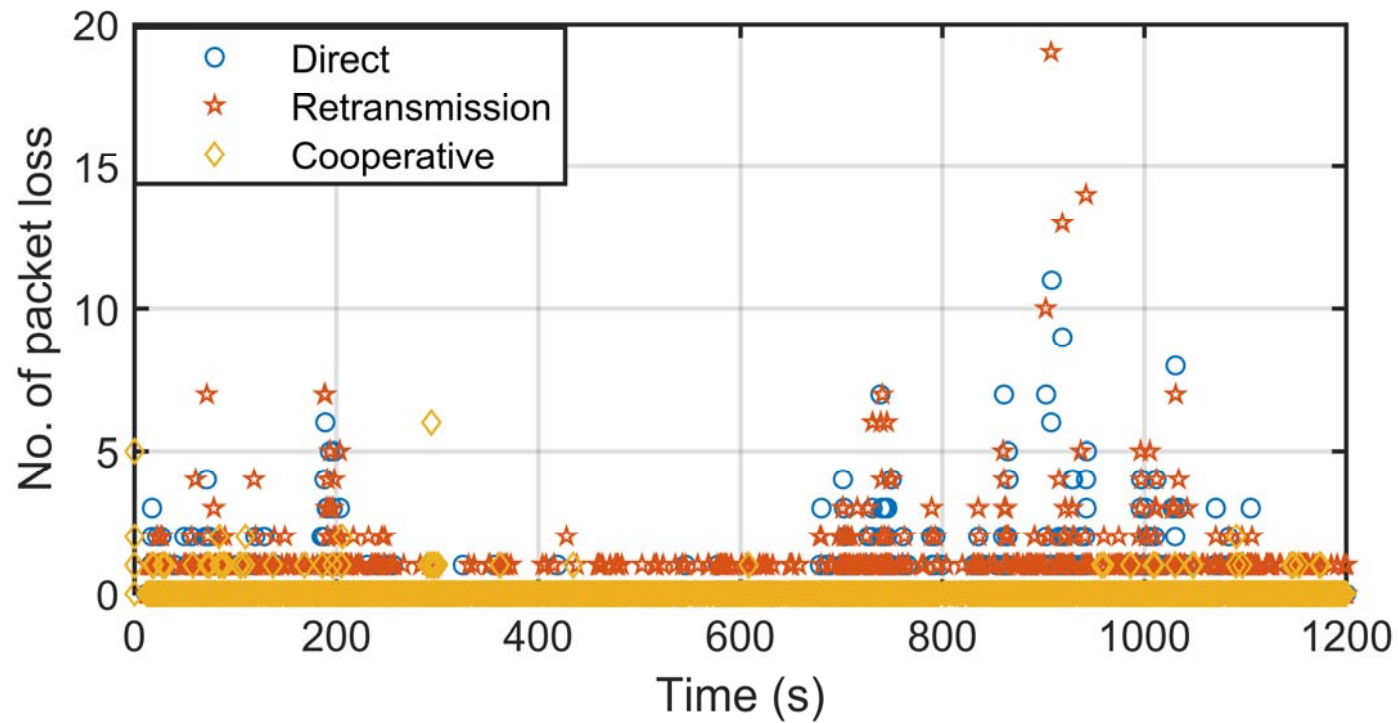


# COOPERATIVE RELAYING



- ❖ Creation of diversity to combat multipath fading effects.
- ❖ A spectral efficient technology with enhanced diversity and coding gains.

# COOPERATIVE RELAYING PERFORMANCE – PACKET LOSS



# PROTOCOLS AND OPTIMIZATION ALGORITHMS

- ❖ Dynamic spectrum access
- ❖ Cooperative path selection (sparse matrix)
- ❖ Data partitioning + path diversity + erasure coding → **anti cyber attack.**
- ❖ Heterogeneity settings
- ❖ Adaptive convergent algorithms for minimizing service disconnection time

# CONCLUSION

- ❖ This is an extremely complex environment for ensuing reliable and robust wireless communications – effective and sustainable technologies in this domain are yet to be properly established and confirmed.
- ❖ Multipath fading effect is much worse than in other types of indoor environment.
- ❖ Small-scale fading is much more dominant than large-scale fading, location dependable and with more Rayleigh channel influence → high loss rates are likely.
- ❖ Key to maintaining a high level of robustness is the creation of diversity in various formats – from trading between reliability and data rate to cross-layer optimization operated in an adaptive manner.





THANK YOU