Brain, Child, Self and Toy Robots: Enrobotment

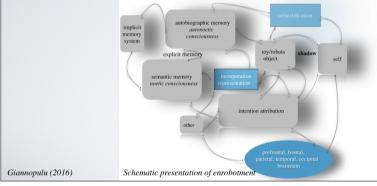
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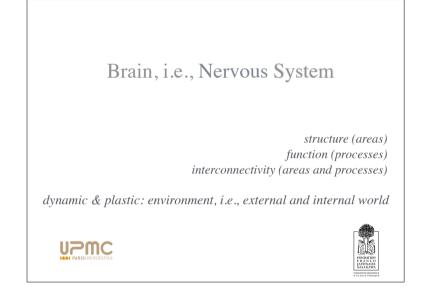
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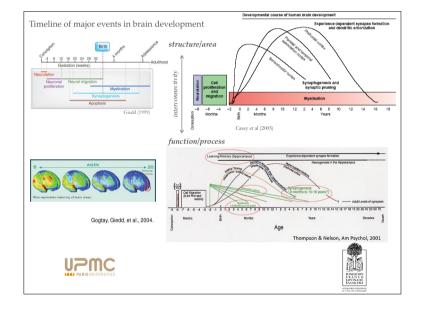
Outline

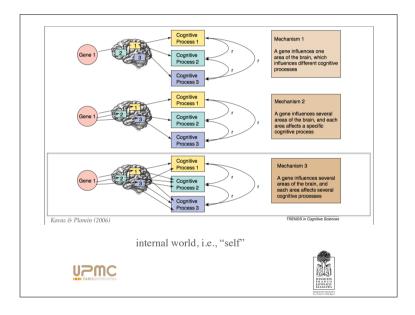
- Enrobotment as a concept
- Embryogenesis of the Brain
- Child verbal, nonverbal and emotional neurocognitive development and the "self"
- Self-conscious and unconscious development and toy robots

Emanating from an interdisciplinary approach, enrobotment is a new concept. Enrobotment is a state of mind that mirrors the internalisation, incorporation and representation of animate and inanimate objects (toys or toy robots) and their shadows, i.e., "imperceptible" and "insignificant" parcel of each object. Enrobotment is intimately associated with the development of verbal, nonverbal (e.g. visual, haptic, motor) and emotional processes. As the echo of the "self", it facilitates self-consciousness.









From 0 to 2 years old: children start to represent objects/toys via manipulation

From 2 to 7 years old: children play with objects/toys by pretending that the objects/toys represent something else, *i.e.*, *symbolic play*, (e.g. a pencil is a microphone) that they like or not. They are very imaginative

From 7 to 11 years old: they understand the roles and the strategies symbolically via objects/toys

Toys provide an interesting account of "how" physical objects presented in the external world are able to act as support for the symbolic play of children, i.e., the internal world

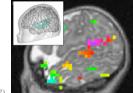




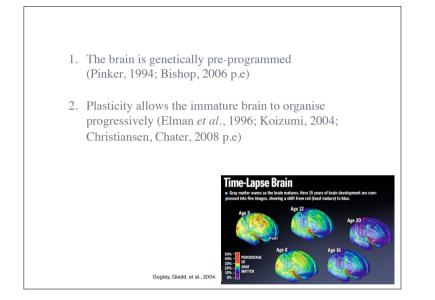
Symbolic play, i.e., the emergence of the "self", is the developmental echo of language and emotion

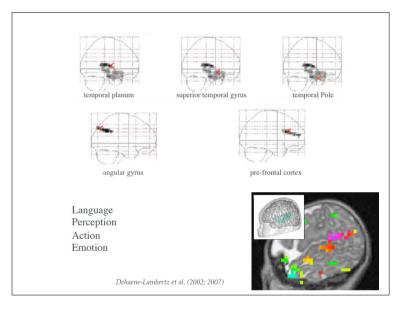
Giannopulu (2016)

Language learning in typically developing children aged 5 to 6 years



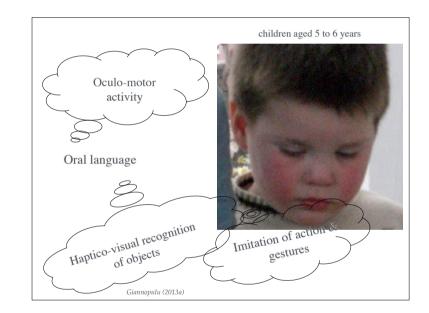
Dehaene-Lambertz et al. (2002; 2007)

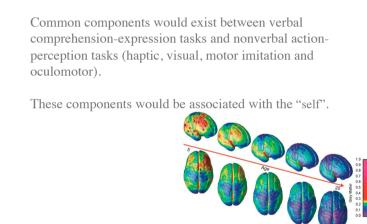






Language learning is possible because of the interaction between different information, i.e., nonverbal information (Bates, 1999).





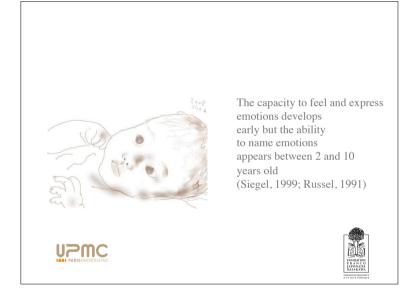
Gogtay, Giedd, et al., 2004

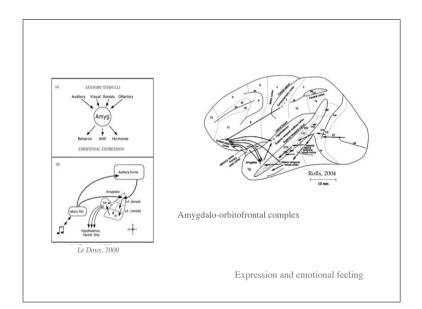
Giannopulu (2013a)

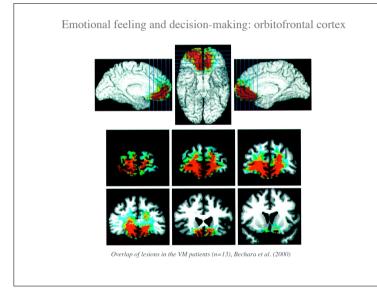
Positive emotion and decision making process in a/typical developing children aged 8 years

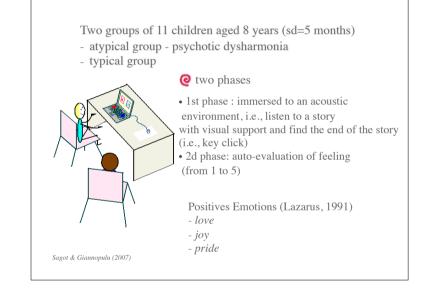
UPMC

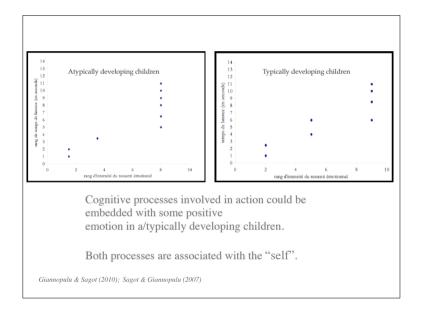


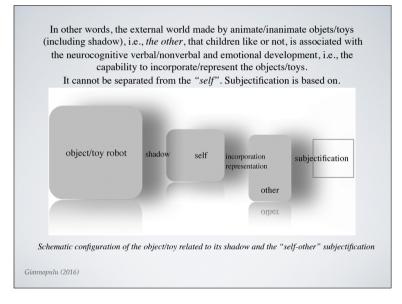


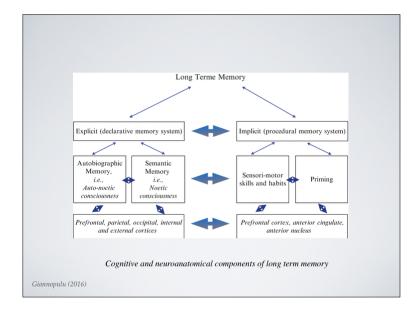


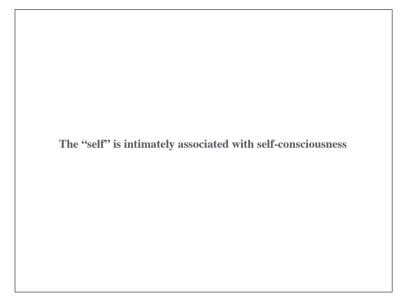




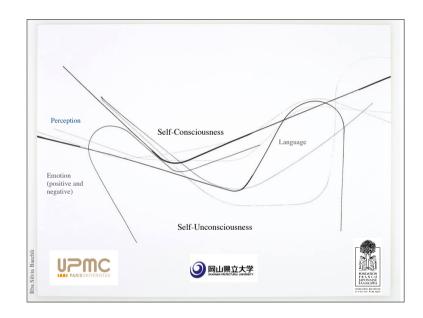


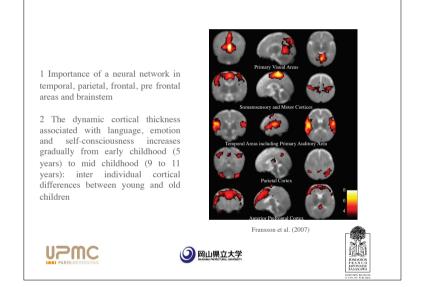


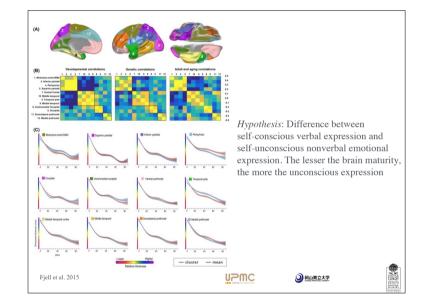




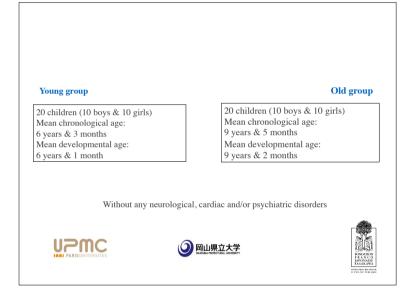




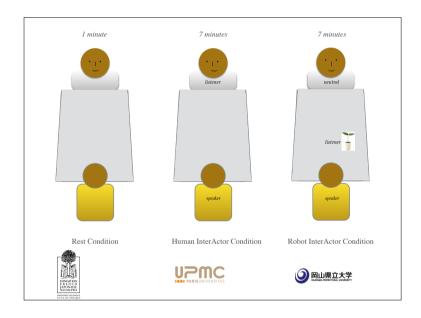


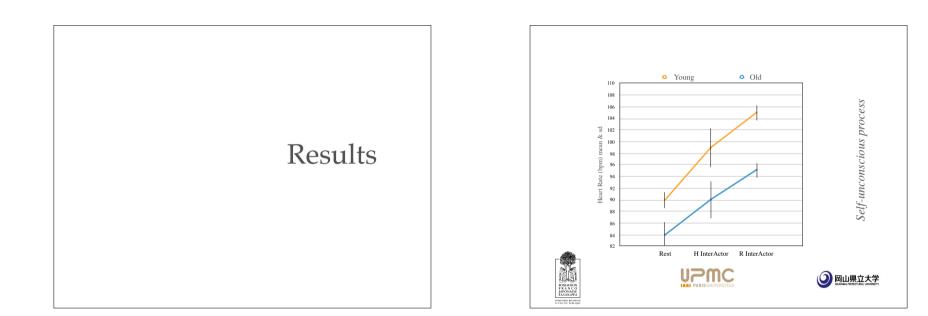


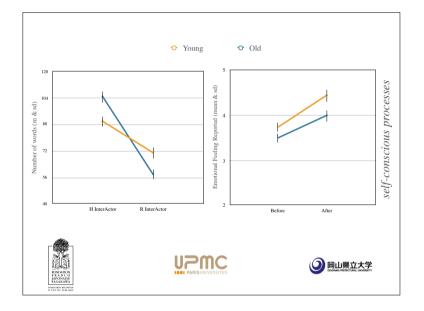
Method Paradigm of "Speaker-Listener"

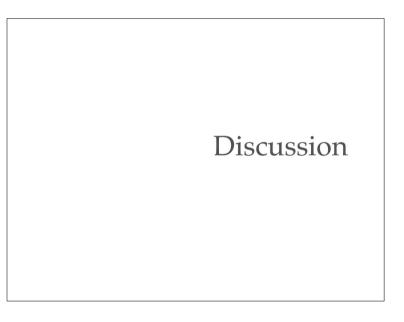


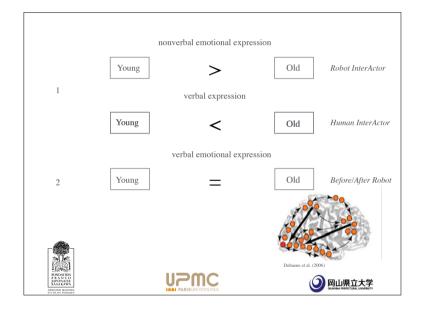


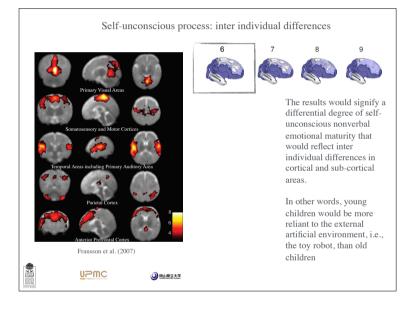


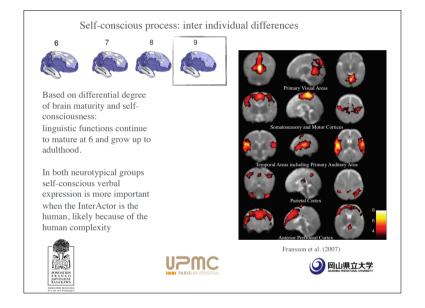












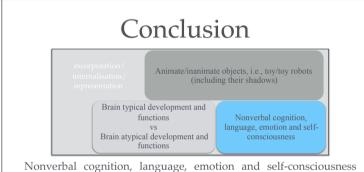
Conclusion

Nonverbal emotional behavior expressed by heart rate is an self-unconscious automatic activity which would depend on an external "artificial" world: the InterActor Robot.

Verbal behavior expressed by the words (nouns and verbs) is a self-conscious activity which would depend on an external "natural" world: the Human InterActor.

Self-Conscious and self-unconscious processes would not only depend on natural external world but also on artificial external world, i.e., toy robots.

Giannopulu & Watanabe, (2015)



Nonverbal cognition, language, emotion and self-consciousness would arise from the dynamic interaction between the developing brain and the object/toy robot (including shadow), i.e., the enrobotment. Enrobotment mirrors the triadic relationship between the "object/toy, self and other". At the antipode, children with autism cannot mirror the triadic relationship of "object/toy, self and other".

Giannopulu (2016)

